Lecture 03.07 Exact analytical transient response characteristics of first- and second-order systems

03.07.1 First-order systems

First-order systems without zeros have transient responses characterized by a *time-constant* τ that appears in the total response as

time-constant

$$_e^{-t/\tau} + _. \tag{03.34}$$

The transient exponential decays such that in three time constants 3τ only 5 % of the term remains; in 5τ , less than 1 %.

There is neither peak nor overshoot for this type of response. However, the rise time for these systems is found from the solution to the first-order rise time input-output ode for y(0) = 0:

$$y(t) = Kb_0 \left(1 - e^{-t/\tau}\right).$$
 (03.35)

The rise time is, by definition, the duration of the time interval $[t_1, t_2]$ such that

$$y(t_1) = 0.1y_{ss}$$
 to $y(t_2) = 0.9y_{ss}$. (03.36)

The first of these yields

$$\mathsf{Kb}_{0}\left(1-e^{-\mathsf{t}_{1}/\tau}\right)=0.1\mathsf{Kb}_{0}\Rightarrow \qquad (03.37a)$$

 $t_1 = -\tau \ln 0.9$ (03.37b)

$$\approx 0.1054\tau. \tag{03.37c}$$

Solving in an analogous fashion, we find $t_2 \approx 2.3026\tau$. The interval, then, is $t_2 - t_1 = 2.1972\tau$.

Equation 03.38 first-order system rise time

Finally, the settling time can be derived in a fashion similar to the rise settling time time.

3 September 2018, 17:29:26

Chapter 03 Measurement systems as dynamia say offer the Transient response characteristics

Equation 03.39 first-order system settling time

03.07.2 Second-order systems

Second-order system transient responses are characterized by a natural frequency ω_n and damping ratio ζ . Following a procedure very similar to that for first-order systems, the following relationships can be derived.

The *rise time* T_r does not have an analytical solution in terms of ω_n and ζ . However, Figure 03.11 can be developed, numerically.

peak time

rise time

The *peak time* T_p has the following, simple expression

$$T_{p} = \frac{\pi}{\omega_{d}}, \qquad (03.40)$$

where $\omega_d = \omega_n \sqrt{1 - \zeta^2}$ is the damped natural frequency. The *percent overshoot* %OS is related directly to ζ as follows

$$\text{\%OS} = 100 \exp \frac{-\zeta \pi}{\sqrt{1-\zeta^2}} \quad \Leftrightarrow \quad \zeta = \frac{-\ln(\text{\%OS}/100)}{\sqrt{\pi^2 + \ln^2(\text{\%OS}/100)}}.$$
 (03.41)

settling time

time Finally, the *settling time* T_s is expressed as

$$T_s = \frac{4}{\zeta \omega_n}.$$
 (03.42)

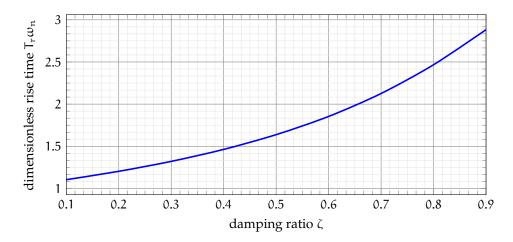


Figure 03.11: the relationship between rise time and damping ratio.