Notes on Generalized Impedances by J. L. Garbini

Generalized impedances are an extension of the concept of electrical impedances to systems of other domains. The table below lists the corresponding driving-point impedance definitions for five different energy modalities.

		Mechanical Translational	Mechanical Rotational	Electrical	Fluid	Thermal
Across Variable		<i>v,</i> velocity	ω, angular velocity	v, voltage	<i>p</i> , pressure	<i>T</i> , temperature
Through Variable		<i>f,</i> force	<i>T</i> , torque	<i>i,</i> current	<i>q,</i> volumetric flow	<i>q,</i> heat flow rate
Impedance $Z(s)$ Admittance $Y(s) = \frac{1}{-1}$		$Z(s) = \frac{V(s)}{F(s)}$	$Z(s) = \frac{\Omega(s)}{T(s)}$	$Z(s) = \frac{V(s)}{I(s)}$	$Z(s) = \frac{P(s)}{Q(s)}$	$Z(s) = \frac{T(s)}{Q(s)}$
	Z(s)					
Impedance Z(s)	А-Туре	$\frac{1}{Ms}$	$\frac{1}{Js}$	capacitor, C $\frac{1}{Cs}$	fluid capacitor, C $\frac{1}{Cs}$	thermal capacitor, C $\frac{1}{Cs}$
	D-Type	damper, B $\frac{1}{B}$	r. damper, B <u>1</u> B	resistor, R R	fluid resistor, R R	thermal resistor, R R
	Т-Туре	spring, K <u>s</u> K	r. spring, K_r $\frac{s}{K_r}$	inductor, L Ls	fluid inductor, L Ls	—

Series and parallel combinations of impedances and admittances can be combined. In the following V and F represent the across and through variables respectively of any physical domain.



Simple transfer functions can be determined from impedance/admittance properties.

Across Variable Divider		Through Variable Divider	
The complex amplitude of the <i>across variable</i> across a set of elements in <i>series</i> is divided among the elements in proportion their <i>impedances</i> .	$V_{s} \bigvee Z_{2} V_{2}$ $Z_{3} = \frac{V_{2}(s)}{V_{s}(s)} = \frac{Z_{2}}{Z_{1} + Z_{2} + Z_{3}}$	The complex amplitude of the <i>through variable</i> through a set of elements in <i>parallel</i> is divided among the elements in proportion their <i>admittances</i> .	$F_{s} \bigvee Y_{1} Y_{2} Y_{3} \forall F_{s}$ $T(s) = \frac{F_{3}(s)}{F_{s}(s)} = \frac{Y_{3}}{Y_{1} + Y_{2} + Y_{3}}$

Thevenin and Norton equivalent networks are useful deriving transfer functions and in modeling systems that have a defined load impedance.

Linear
Network
V _e Linear Network V _e



Source Transformations	
Since any linear two-terminal networks can be represented by either a Thevenin equivalent or a Norton equivalent, the two representations must be equivalent to each other.	$V_{e} \bigvee Z_{e} \longrightarrow F_{e} \bigvee Z_{e}$ $F_{e} = \frac{V_{e}}{Z_{e}}$

Note: In both Thevenin and Norton networks the impedance Z_e is determined by finding the impedance at the terminals with all of the sources set equal to zero. The sources are set to zero, as follows:

- Across Variable Source: *Replace* the across variable source with a short circuit. That is, the nodes to which the source is connected are joined together.
- **Through Variable Source**: *Remove* the through variable source from the network.

Measurement Loading

Across Variable Measurements

Suppose that we wish to measure an across variable at the output of a "device under test" with a "measurement instrument." The measurement instrument is attached across the terminals of interest. Of course we desired that the measured variable be undisturbed by the connection of the instrument. That is, we want V_m to be as nearly equal to V_o as possible. We say that the measurement instrument should not "load" the device under test.

The *output impedance* of the device under test is the equivalent impedance defined by its Thevenin model $Z_0 = Z_e$ for the unloaded output (disconnected) terminals.

Similarly, the *input impedance* Z_i of the measurement instrument is the Thevenin equivalent impedance defined for its input terminals.

Connecting the Thevenin model for the device under test to the input impedance of the measurement instrument we have the network at the right.

The Thevenin equivalent across variable source is by definition equal to V_o , the value that we wish to measure. Applying the across

variable divider rule: $\frac{V_m(s)}{V_o(s)} = \frac{1}{1 + Z_o/Z_i}$.

Since we desire that the ratio approach unity, the input impedance of the measurement instrument must be large in comparison with the output impedance of the device under test: $Z_i >> Z_o$

Through Variable Measurements

Alternately, suppose that we wish to measure a through variable in a device under test with a measurement instrument. In this case, the variable of interest flows through the measurement instrument. We desired that the measured variable be undisturbed by the connection of the instrument. That is, we want F_m to be as nearly equal to F_0 as possible.

The *output admittance* of the device under test is the equivalent admittance defined by its Norton's model $Y_0 = 1/Z_e$ for the unloaded (disconnected) output terminals.

Similarly, the *input admittance* Y_i of the measurement instrument is the Norton equivalent admittance defined for its input terminals.

Connecting the Norton model for the device under test to the input admittance of the measurement instrument we have the network at the right.

The Norton equivalent through variable source is by definition equal to F_0 , the value that we wish to measure. Applying the through

variable divider rule: $\frac{F_m(s)}{F_o(s)} = \frac{1}{1 + Y_o/Y_i}$.

Since we desire that the ratio approach unity, the input admittance of the measurement instrument must be large in comparison with the output admittance of the device under test: $Y_i >> Y_o$







