

## 11.2 lap.def Laplace transform and its inverse

### The Laplace transform

**1** The two-sided definition of the Laplace transform was encountered in [Lec. 11.1 lap.in](#). This is rarely used in engineering analysis, which prefers the following one-sided transform.<sup>2</sup>

#### Definition 11 lap.2: Laplace transform

Let  $f : \mathbb{R}_+ \rightarrow \mathbb{R}$  be a function of time  $t$  for which  $f(t) = 0$  for  $t < 0$ . The Laplace transform<sup>3</sup>  $\mathcal{L} : T \rightarrow S$  of  $f$  is defined as<sup>4</sup>

$$(\mathcal{L}f)(s) = \int_0^{\infty} f(t)e^{-st} dt.$$

**2** As with the Fourier transform image, it is customary to \_\_\_\_\_ the Laplace transform image; e.g.<sup>5</sup>

$$F(s) = (\mathcal{L}f)(s).$$

**3** As with the two-sided Laplace transform, if the transform exists, it will do so for some region of convergence (ROC), a subset of the  $s$ -plane. It is best practice to report a Laplace transform image paired with its ROC.

**4** On the imaginary axis ( $\sigma = 0$ ),  $s = j\omega$  and the Laplace transform is

$$(\mathcal{L}f)(s) = \int_0^{\infty} f(t)e^{-j\omega t} dt, \quad (1)$$

which is the one-sided Fourier transform! Therefore, when the Laplace transform exists for a region of convergence that \_\_\_\_\_

<sup>2</sup>We will refer exclusively to the one-sided transform as the Laplace transform and will qualify “two-sided” in the other case.

<sup>3</sup>Here  $T = L^2(0, \infty)$  is the set of square-integrable functions on the positive reals and  $S = H^2(\mathbb{C}_+)$  is a Hardy space with square norm on the (complex) right half-plane (Partington, 2004, p. 7). This highly mathematical notation highlights the fact that the Laplace transform maps a real function of  $t$  to a complex function of  $s$ .

<sup>4</sup>For more detail, see Rowell and Wormley (1997), Dyke (2014), and Mathews and Howell (2012).

<sup>5</sup>Another common notation is  $\mathcal{L}(f(t))$ .

\_\_\_\_\_, the one-sided Fourier transform also exists and<sup>6</sup>

$$(\mathcal{F}f)(\omega) = (\mathcal{L}f)(s)|_{s \mapsto j\omega} \quad (2)$$

or, haphazardly using  $F$  to denote both transforms,

$$F(\omega) = F(s)|_{s \mapsto j\omega}. \quad (3)$$

### Box 11 lap.1 Laplace terminology

The terminology in the literature for the Laplace transform and its inverse, introduced next, is inconsistent. The “Laplace transform” is at once taken to be a function that maps a function of  $t$  to a function of  $s$  and a particular result of that mapping (technically the *image* of the map), which is a complex function of  $s$ . Even we will say things like “the value of the Laplace transform  $F(s)$  at  $s = 2 + j4$ ,” by which we really mean the image of the complex function  $F(s)|_{s \rightarrow 2+j4}$  that was the image of the Laplace transform map of the real function of time  $f(t)$ . You can see why we shorten it.

## The inverse Laplace transform

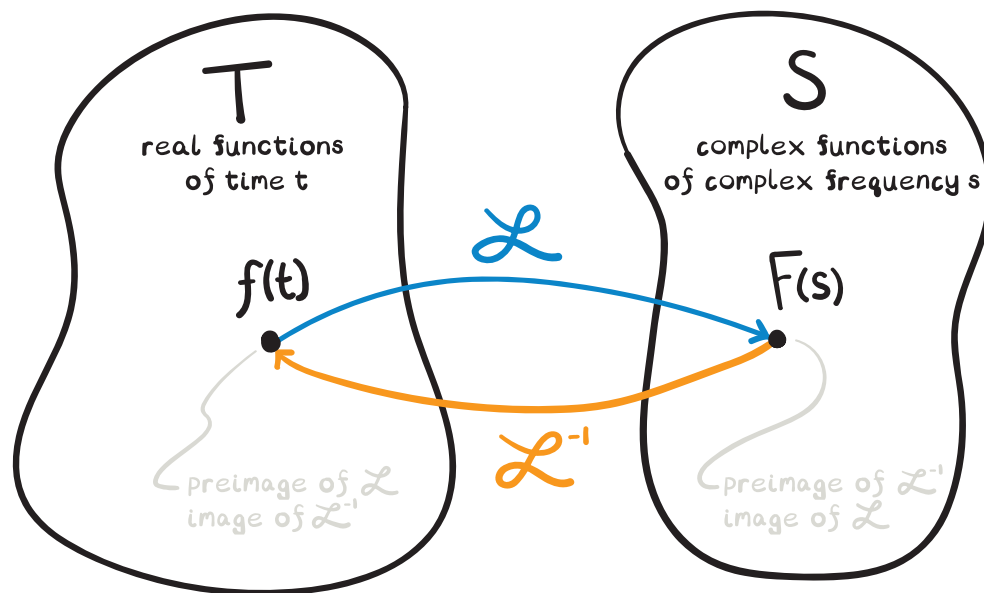
5 As with the Fourier transform, the Laplace transform has an \_\_\_\_\_.

### Definition 11 lap.3: Inverse Laplace transform

Let  $s \in \mathbb{C}$  be the Laplace  $s$  and  $F(s)$  a Laplace transform image of real function  $f(t)$ . The *inverse Laplace transform*  $\mathcal{L}^{-1} : S \rightarrow T$  is defined as

$$(\mathcal{L}^{-1}F)(t) = \frac{1}{j2\pi} \int_{\sigma-j\infty}^{\sigma+j\infty} F(s)e^{st} ds.$$

<sup>6</sup>The same relation can be shown to hold between the two-sided Fourier and Laplace transforms.

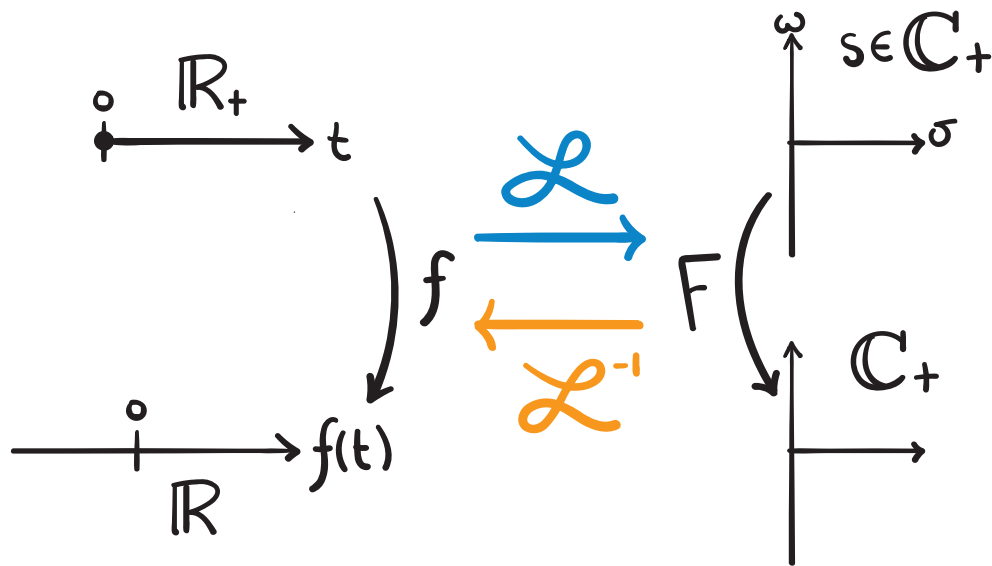


**Figure def.1:** Laplace transform maps  $\mathcal{L}$  and  $\mathcal{L}^{-1}$  on the function spaces  $T$  and  $S$ .

As is illustrated in Fig. def.1, it can be shown that the inverse Laplace transform image of a Laplace transform image of  $f(t)$  equals  $f(t)$  and vice-versa; i.e.

$$(\mathcal{L}^{-1}\mathcal{L}f)(t) = f(t) \quad \text{and} \\ (\mathcal{L}\mathcal{L}^{-1}F)(s) = F(s).$$

That is, the inverse Laplace transform is a true inverse. Therefore, we call the Laplace transform and its inverse a                     .



**Figure def.2:** detail view of Laplace transform maps  $\mathcal{L}$  and  $\mathcal{L}^{-1}$  along with their image functions  $f$  and  $F$ .

6 A detail view of Fig. def.1 is given in Fig. def.2.

### Example 11.2 lap.def-1

Returning to the troublesome unit step  $f(t) = u_s(t)$ , calculate its Laplace transform image  $F(s)$ .

Directly applying the definition,

$$\begin{aligned}
 F(s) &= \int_0^{\infty} f(t)e^{-st} dt \\
 &= \underline{\hspace{2cm}} \\
 &= \frac{-1}{s} e^{-st} \Big|_{t=0}^{\infty} \\
 &= \left( \lim_{t \rightarrow \infty} -e^{-(\sigma+j\omega)t}/s \right) - \frac{-1}{s} e^0 \quad (s = \sigma + j\omega) \\
 &= 1/s. \quad (\sigma > 0)
 \end{aligned}$$

Note that the limit only converges for  $\sigma > 0$ , so the region of convergence

is the right half  $s$ -plane, exclusive of the imaginary axis. This exclusion tells us what we already know, that the Fourier transform  $u_s$  does not exist. However, the Laplace transform *does* exist and is simply  $1/s$ !

7 Both the Laplace transform and especially its inverse are typically calculated with the help of software and tables such as [Table lap.1](#), which includes specific images and important properties. We will first consider these properties in [Lec. 11.3 lap.pr](#), then turn to the use of software and tables in [Lec. 11.4 lap.inv](#) where we focus on the more challenging inverse calculation.