

## 14.3 nlin.exe Exercises for Chapter 14 nlin

### Exercise 14.1 sigmund

Consider a nonlinear capacitor with constitutive equation relating charge  $q_C$  and voltage  $v_C$ :

$$q_C = kv_C^{3/2} \quad (1)$$

with  $k$  a positive constant.

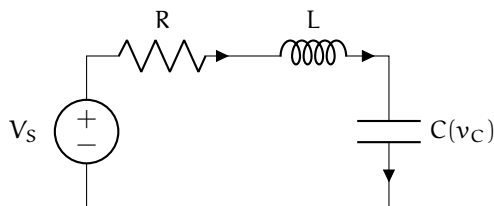
- Derive an elemental equation relating  $dv_C/dt$  and  $i_C$  for the nonlinear capacitor.
- From the elemental equation, what is the voltage-dependent capacitance  $C(v_C)$ ?
- Consider the RLC-circuit of Fig. exe.1, which includes the nonlinear capacitor. Derive a nonlinear state-space equation with state vector

$$\mathbf{x} = \begin{bmatrix} v_C & i_L \end{bmatrix}^T. \quad (2)$$

- For a constant input  $V_S(t) = 5 \text{ V}$ , derive the equilibrium state.
- Linearize the state-space equation about the operating point

$$\mathbf{x}_o, \mathbf{u}_o = \begin{bmatrix} 5 \text{ V} & 0 \text{ A} \end{bmatrix}^T, \begin{bmatrix} 5 \text{ V} \end{bmatrix}. \quad (3)$$

Define the state equation matrices  $A$  and  $B$ , the linearized state and input vectors  $\mathbf{x}^*$  and  $\mathbf{u}^*$ , and the linearized state equation.



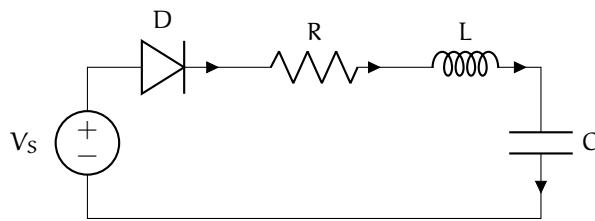
**Figure exe.1:** circuit for Exercise 14.1 nlin..

**Exercise 14.2 franz**

A nonlinear diode model gives a diode's elemental equation to be

$$i_D = I_s (\exp(v_D/V_{TH}) - 1).$$

We let the saturation current be  $I_s = 10^{-12}$  A and the thermal voltage be  $V_{TH} = 0.025$  V. Considering this nonlinear diode model for the circuit of Fig. exe.2.



**Figure exe.2:** circuit for Exercise 14.2 nlin..

- a. Derive a nonlinear state-space equation with state vector

$$\mathbf{x} = \begin{bmatrix} v_C & i_L \end{bmatrix}^T. \quad (4)$$

*Hint: include the diode in your normal tree.*

- b. For a constant input  $V_s(t) = 0$  V, derive the equilibrium state.  
 c. Linearize the state-space equation about the operating point

$$\mathbf{x}_o, \mathbf{u}_o = \begin{bmatrix} 0 \text{ V} & 0 \text{ A} \end{bmatrix}^T, \begin{bmatrix} 0 \text{ V} \end{bmatrix}. \quad (5)$$

*Hint:  $d \ln(x)/dx = 1/x$ . Define the state equation matrices A and B, the linearized state and input vectors  $\mathbf{x}^*$  and  $\mathbf{u}^*$ , and the linearized state equation.*

**15 phase**

---

**16 sim**

---