

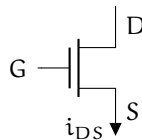
04.3 *nlnmul.fet* MOSFETs

A metal–oxide–semiconductor field-effect transistor (MOSFET) is a *two-port, nonlinear* circuit element that lies at the heart of digital electronics, with sometimes millions integrated into a single microprocessor. They are the dominant type of **transistor**, a class of elements that includes the **bipolar junction transistor (BJT)**.

MOSFETs are not just common in integrated circuits made of silicon, they are also available as discrete elements, which is the form most often encountered by the mechatronicist.

There are two primary types of MOSFET: the **n-channel** and the **p-channel**, determined by the type of semiconductor doping (negative or positive) used in the manufacturing process. These types are “opposites,” so we choose to focus on n-channel, here.

Fig. *fet.1* displays the circuit diagram symbol for the MOSFET. There are three⁴ terminals: the **gate G**, **drain**



D, and **source S**. The current flowing from one terminal to another is labeled with

Figure fet.1:
circuit symbol
for a n-channel
MOSFET.

consecutive subscripts; for instance, the current flowing from drain to source is i_{DS} . Similarly, the voltage drop across two terminals is labeled with concurrent subscripts; for instance, the voltage drop from gate to source is v_{GS} .

The input-output characteristics of the MOSFET are quite complex, but we may, in the first approximation, consider it to be like a *switch*. In this model, called the **S-model**, if the gate voltage v_{GS} is less than the **threshold voltage** V_T (typically around 0.7 V), the D and S terminals are disconnected (open) from each other (OFF mode). But when $v_{GS} > V_T$, D and S

4. Note that if we consider the gate-side to be the input with $i_{GS} = 0$ and v_{GS} and the drain-source-side to be the output with i_{DS} and v_{DS} , the MOSFET can be seen to be two-port.

are connected via a short and current i_{DS} can flow (ON mode).

The input-output characteristics of a MOSFET are actually much more complex than the S-model captures. The S-model can build intuition and suffice for digital logic circuit analysis. However, we are here mostly concerned with analog circuit models.

Specifically, we mechatronicists use MOSFETs to drive power-hungry loads (e.g. motors) with high-power sources controlled by low-power microcontrollers. We now turn to a general model, after which we consider a method of analyzing MOSFET circuits.

The switch unified (SU) model

The **switch unified (SU) model** is reasonably accurate at describing actual MOSFET input-output characteristics. However, it is quite *nonlinear*, and therefore can give us headaches during analysis. As usual, we are concerned with the element's voltage-current relationships.

Definition 04 nlnmul.2: switch unified model

Let K be a constant parameter of the MOSFET with units A/V^2 . K can be found from parameters of a given MOSFET. The current into the gate is zero: $i_G = 0$. The current from drain to source is controlled by the two voltage variables v_{GS} and v_{DS} , as shown.

$$i_{DS} = \begin{cases} 0 & \text{for } v_{GS} < V_T \\ K((v_{GS} - V_T)v_{DS} - v_{DS}^2/2) & \text{for } v_{GS} \geq V_T \text{ and } v_{DS} < v_{GS} - V_T \\ \frac{K}{2}(v_{GS} - V_T)^2 & \text{for } v_{GS} \geq V_T \text{ and } v_{DS} \geq v_{GS} - V_T \end{cases}$$

So, as in the S-model, the gate voltage v_{GS} must exceed the threshold voltage V_T for current to flow. The interval below the threshold is called the **cutoff region** (OFF). Note, however, that current doesn't just flow freely, as it would with

the short of the S-model. In fact, two distinct ON ($v_{GS} > V_T$) intervals emerge. In both, the current i_{DS} depends on v_{GS} . In the **triode region**, $v_{DS} < v_{GS} - V_T$, i_{DS} also depends on v_{DS} . However, in the **saturation region**, $v_{DS} > v_{GS} - V_T$, i_{DS} is independent of v_{DS} and can be controlled by v_{GS} , alone.

Note that in saturation, the MOSFET behaves like a current source controlled by v_{GS} . A source controlled by a variable in the circuit is called a **dependent source**. This behavior as a dependent current source (that can also be turned off) is the most valuable for us.

The **switch current source (SCS) model** is actually just a recognition of this behavior and an elimination of the triode region from consideration. This is a reasonable assumption if we can guarantee operation in cutoff or saturation only.

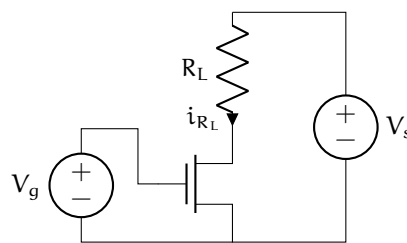
Given the piecewise MOSFET models, we can again use the **method of assumed states** for MOSFET circuit analysis. Note however that only the S-model is piecewise linear and that the SU- and SCS-models are piecewise nonlinear. We can handle some relatively simple nonlinear cases analytically, but require either linearization or numerical assistance for more complex circuit analyses.

Example 04.3 *nlnmul.fet-1*

re: transformers and impedance

Given the circuit shown, solve for the voltage across the load R_L for varying V_g given the following conditions:

- saturation of the MOSFET, $R_L = 1$ k Ω , $K = 0.5$ mA/V²,
- $V_T = 0.7$ V, $V_s = 10$ V.
- V.





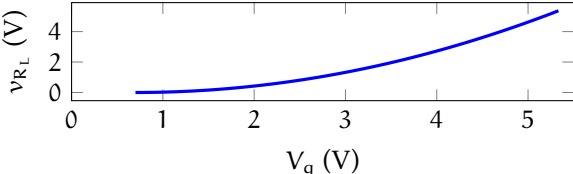


Figure fet.2: the load voltage as a function of gate voltage for Example 04.3 nlnmul.fet-1.