

### 3.6 Probability Density and Mass Functions



Consider an experiment that measures a random variable. We can plot the relative frequency of the measurand landing in different “bins” (ranges of values). This is called a **frequency distribution** or a **probability mass function** (PMF).

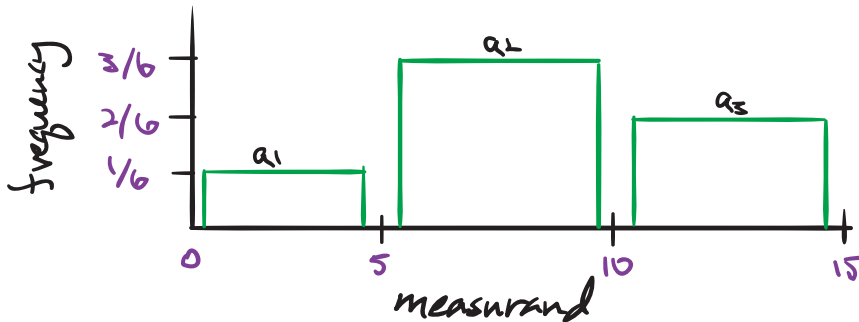


Figure 3.5. Plot of a probability mass function.

Consider, for instance, a probability mass function as plotted in figure 3.5, where a frequency  $a_i$  can be interpreted as an estimate of the probability of the measurand being in the  $i$ th interval. The sum of the frequencies must be unity:

$$\sum_{i=1}^k a_i = 1$$

with  $k$  being the number of bins.

The **frequency density distribution** is similar to the frequency distribution, but with  $a_i \mapsto a_i/\Delta x$ , where  $\Delta x$  is the bin width.

If we let the bin width approach zero, we derive the **probability density function** (PDF)

$$f(x) = \lim_{\substack{k \rightarrow \infty \\ \Delta x \rightarrow 0}} \sum_{j=1}^k a_j / \Delta x.$$

We typically think of a probability density function  $f$ , like the one in figure 3.6 as a function that can be integrated over to find the probability of the random variable (measurand) being in an interval  $[a, b]$ :

$$P(x \in [a, b]) = \int_a^b f(x) dx.$$

Of course,

$$P(x \in (-\infty, \infty)) = \int_{-\infty}^{\infty} f(x) dx = 1.$$

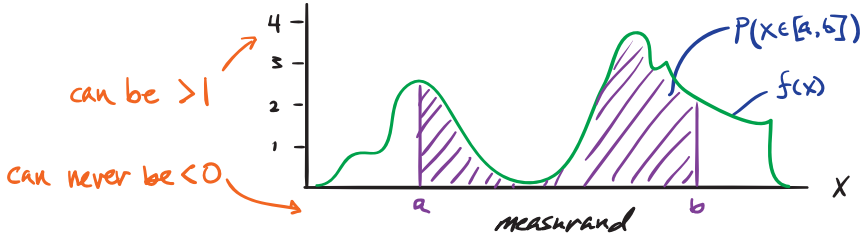


Figure 3.6. Plot of a probability density function.

We now consider a common PMF and a common PDF.

### 3.6.1 Binomial PMF

Consider a random binary sequence of length  $n$  such that each element is a random 0 or 1, generated independently, like

$$(1, 0, 1, 1, 0, \dots, 1, 1).$$

Let events  $\{1\}$  and  $\{0\}$  be mutually exclusive and exhaustive and  $P(\{1\}) = p$ . The probability of the sequence above occurring is

$$P((1, 0, 1, 1, 0, \dots, 1, 1)) = p(1-p)pp(1-p) \cdots pp.$$

There are  $n$  choose  $k$ ,

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}$$

possible combinations of  $k$  ones for  $n$  bits. Therefore, the probability of any combination of  $k$  ones in a series is

$$f(k) = \binom{n}{k} p^k (1-p)^{n-k}.$$

We call section 3.6.1 the **binomial distribution PDF**.

#### Example 3.7

Consider a field sensor that fails for a given measurement with probability  $p$ . Given  $n$  measurements, plot the binomial PMF as a function of  $k$  failed measurements for a few different probabilities of failure  $p \in [0.04, 0.25, 0.5, 0.75, 0.96]$ .

listing 3.1 shows Python code for constructing the PDFs plotted in figure 3.7. Note that the symmetry is due to the fact that events  $\{1\}$  and  $\{0\}$  are mutually exclusive and exhaustive.

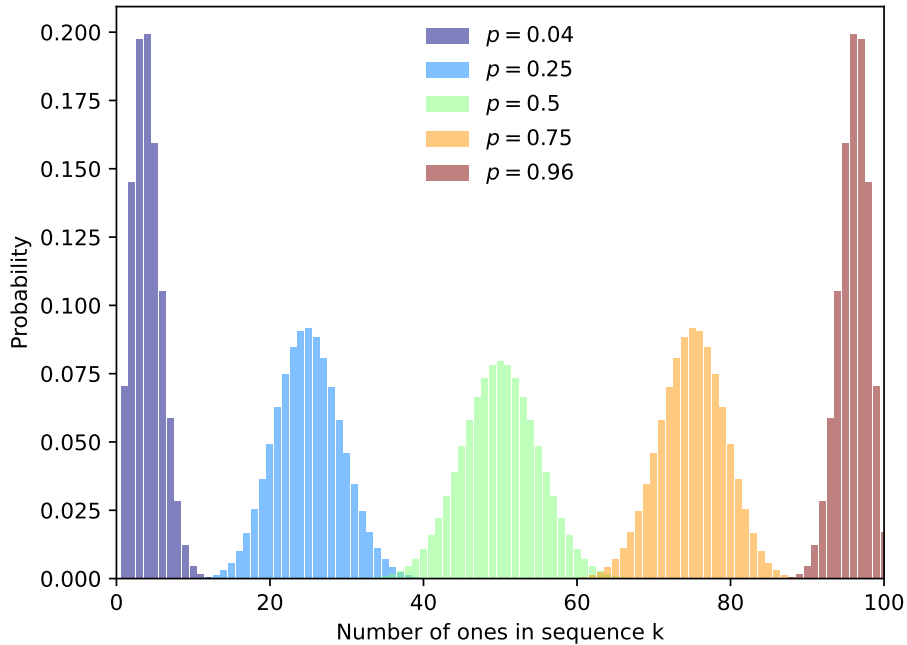


Figure 3.7. Binomial PDF for  $n = 100$  measurements and different values of  $P(\{1\}) = p$ , the probability of a measurement error. The plot is generated by the Python code of ??.

Listing 3.1 Python code that generates the binomial PDF

```

import numpy as np
import matplotlib.pyplot as plt
from scipy.special import comb

# Parameters
n = 100
k_a = np.arange(1, n + 1)
p_a = np.array([0.04, 0.25, 0.5, 0.75, 0.96])

# Binomial function
def binomial(n, k, p):
    return comb(n, k) * (p ** k) * ((1 - p) ** (n - k))

# Constructing the array
f_a = np.zeros((len(k_a), len(p_a)))
for i in range(len(k_a)):
    for j in range(len(p_a)):
        f_a[i, j] = binomial(n, k_a[i], p_a[j])

# Plot
plt.figure()
colors = plt.cm.jet(np.linspace(0, 1, len(p_a)))
for j in range(len(p_a)):
    plt.bar(k_a, f_a[:, j], color=colors[j], alpha=0.5, label=f'$p = \to \{p_a[j]\}$')

plt.legend(loc='best', frameon=False, fontsize='medium')
plt.xlabel('Number of ones in sequence k')
plt.ylabel('Probability')
plt.xlim([0, 100])
plt.show()

# Save the plot to pdf
plt.savefig('binomial-pdf.pdf', bbox_inches='tight')

```

### 3.6.2 Gaussian PDF

The **Gaussian** or *normal random variable*  $x$  has PDF

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp \frac{-(x - \mu)^2}{2\sigma^2}.$$

Although we're not quite ready to understand these quantities in detail, it can be shown that the parameters  $\mu$  and  $\sigma$  have the following meanings:

- $\mu$  is the **mean** of  $x$ ,
- $\sigma$  is the **standard deviation** of  $x$ , and
- $\sigma^2$  is the **variance** of  $x$ .

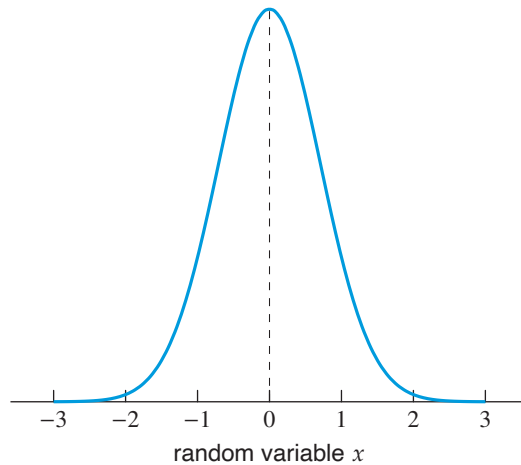


Figure 3.8. PDF for Gaussian random variable  $x$ , mean  $\mu = 0$ , and standard deviation  $\sigma = 1/\sqrt{2}$ .

Consider the “bell-shaped” Gaussian PDF in figure 3.8. It is always symmetric. The mean  $\mu$  is its central value and the standard deviation  $\sigma$  is directly related to its width. We will continue to explore the Gaussian distribution in the following lectures, especially in section 4.3.

### 3.7 Expectation

Recall that a random variable is a function  $X : \Omega \rightarrow \mathbb{R}$  that maps from the sample space to the reals. Random variables are the arguments of probability mass functions (PMFs) and probability density functions (PDFs).

The **expected value** (or **expectation**) of a random variable is akin to its “average value” and depends on its PMF or PDF. The expected value of a random variable  $X$  is denoted  $\langle X \rangle$  or  $E[X]$ . There are two definitions of the expectation, one for a discrete random variable, the other for a continuous random variable. Before we define, them, however, it is useful to predefine the most fundamental property of a random variable, its **mean**.

#### Definition 3.1

The *mean* of a random variable  $X$  is defined as

$$m_X = E[X].$$

Let’s begin with a discrete random variable.

